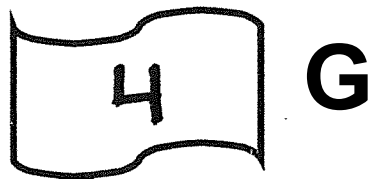


# HIGHWAY ENGINEERING

## GEOMETRIC DESIGN.



# \* Horizontal Alignment \*

## التخطيط الأفقي للطرق

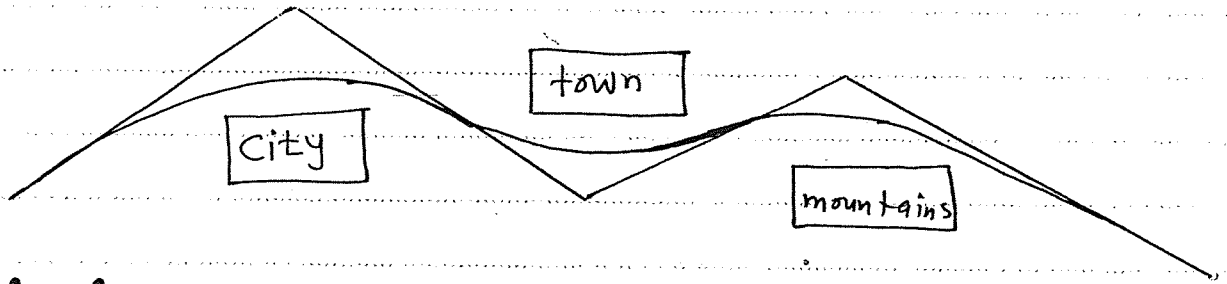
### مقدمة :-

في كثير من الأحيان يواجه المصمم للطرق مهمة وصل الأطوال المستقيمة والمتقاطعة لمسار الطريق بمنحنيات غانيمت تناسب التغير المفاجئ في الاتجاه وتسهل الانتقال بين هذه الأطوال . المنحنيات الأفقية للمنعينات التي تربط بين قطوع التقاطعات في المرات الحقيقية

### العوامل التي تؤثر في تصميم المنحنيات :-

- \* طول عزمية الأضلاع
- \* التقاطع إلى كسر مسار الطريق (المسار القربان) يجب أن يمر بها الطريق
- \* العوامل الاقتصادية
- \* العوائق الموجودة على المسار
- \* السرية التمهيدية

لا حظ وجود المنحنيات الحقيقية في الطريق تزيد من درجة اتجاه السائق عن الطريق المستقيمة أشار القيادة



# Horizontal Alignment

## \* Tangents

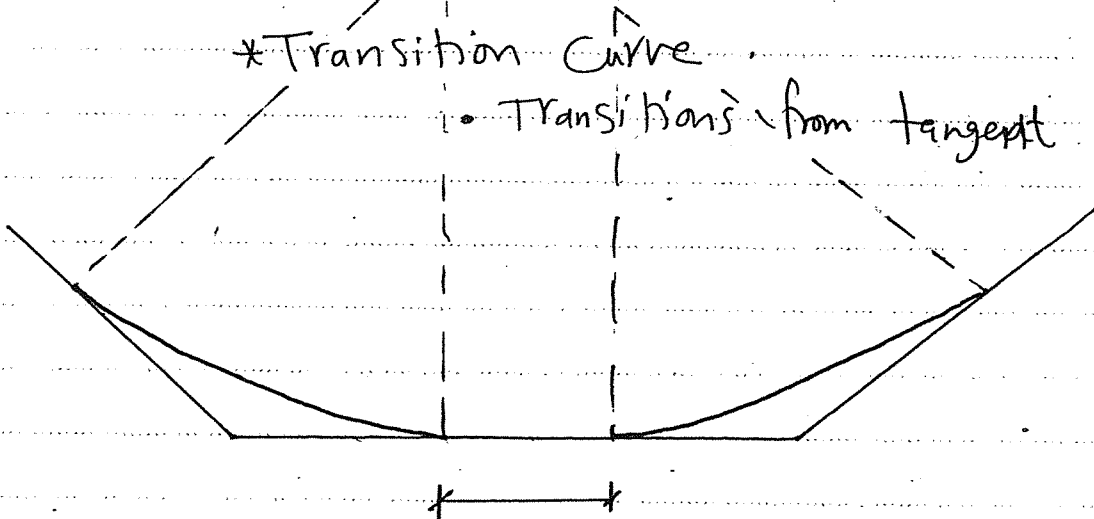
- Straight Segments
- Preferably not more than 20 V
- " not less than 6 V  
(2 V for reverse curves)

## \* Horizontal Curve

- Usually circular
- Simple, compound, reverse
- full superelevation

## \* Transition Curve

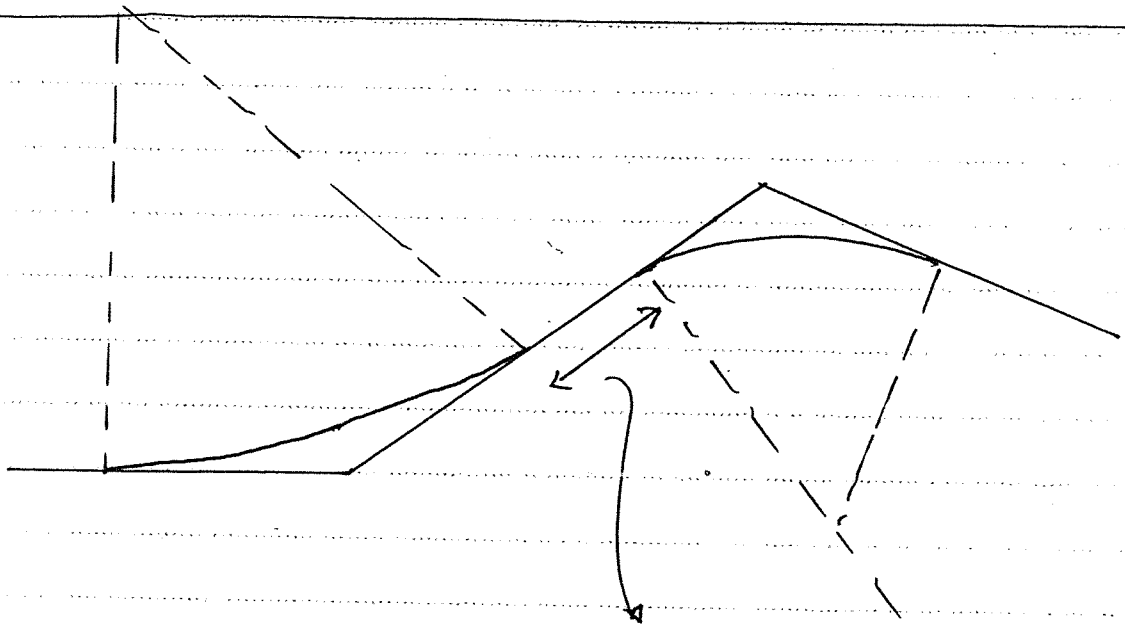
- Transitions from tangent to curve



min = 6 V

max = 20 V

في حالة المركبين في نفس الاتجاه فهناك

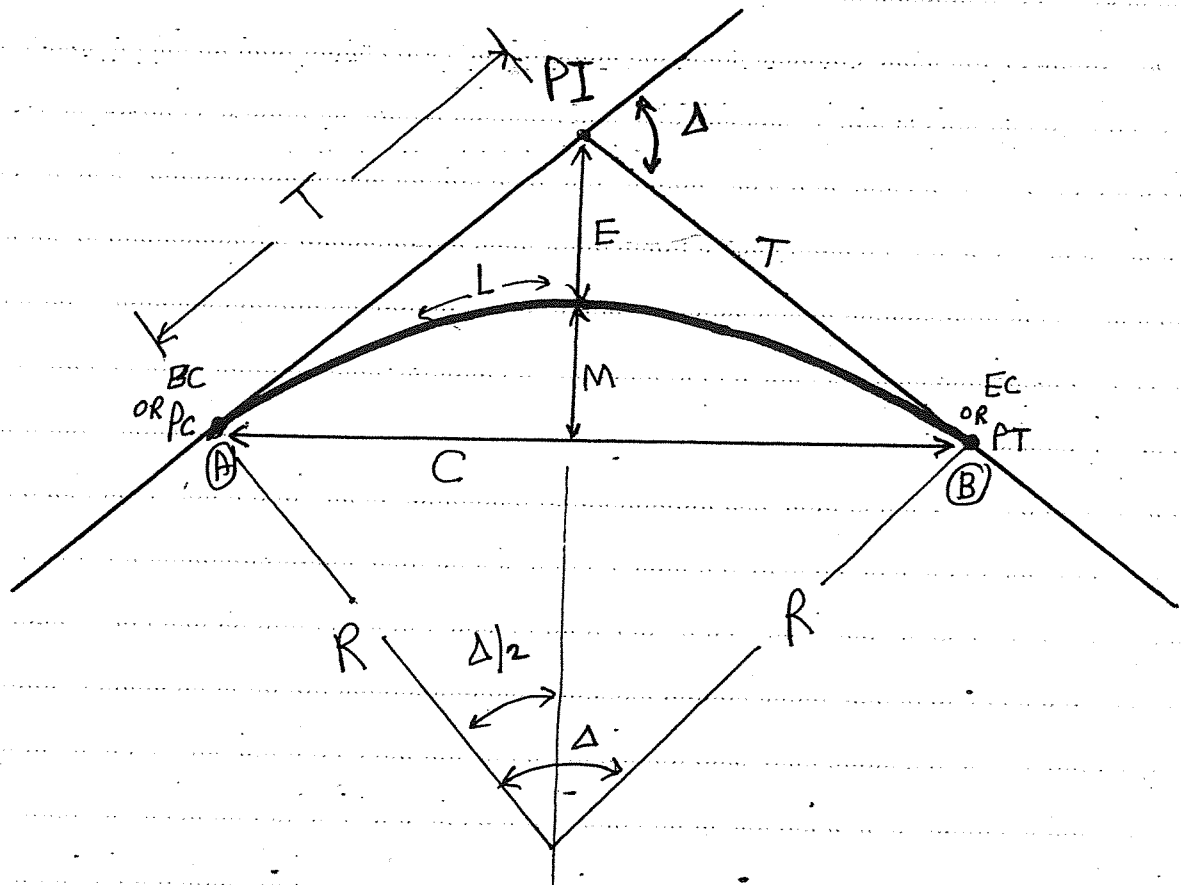


في حالة المركزين من اتجاهين متصلين

•  $\min = 2 \nabla$

•  $\max = 20 \nabla$

## Layout of a simple horizontal Curve



- $R$  :- Radius of Circular Curve
- $BC$  :- Beginning of Curve (OR  $P_c$  = Point of Curvature)
- $EC$  :- End of Curve (OR  $P_T$  = Point of Tangency)
- $PI$  :- Point of Intersection
- $T$  :- Tangent length
- $L$  :- length of Curvature
- $M$  :- Middle ordinate
- $E$  :- External Distance
- $C$  :- Chord length
- $\Delta$  :- Deflection Angle

## Properties of horizontal Curve

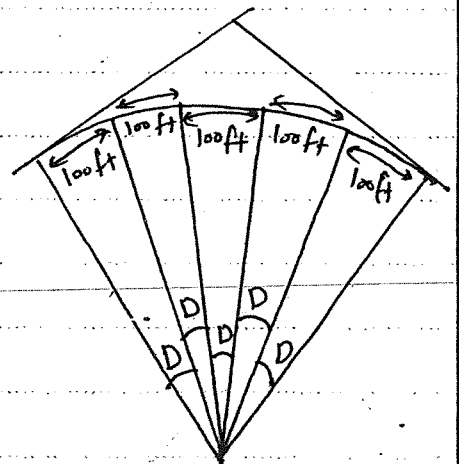
- A circular Curve is described either by its Radius ( $R$ ) or by the Degree of the Curve ( $D$ )
- Degree of Curve is the angle in degrees subtended at the center of a circular arc  $[100] \text{ ft}$

درجة المنحنى هو مقدار الزاوية المركزية بالدرجات التي تصنع قوس من المنحنى بطول 100 قدم  $\equiv [30.48] \text{ m}$

$$L = R \times D \times \frac{\pi}{180}$$

$$30.48 = R \times D \times \frac{\pi}{180}$$

$$R_c = \frac{1746}{D^\circ}$$



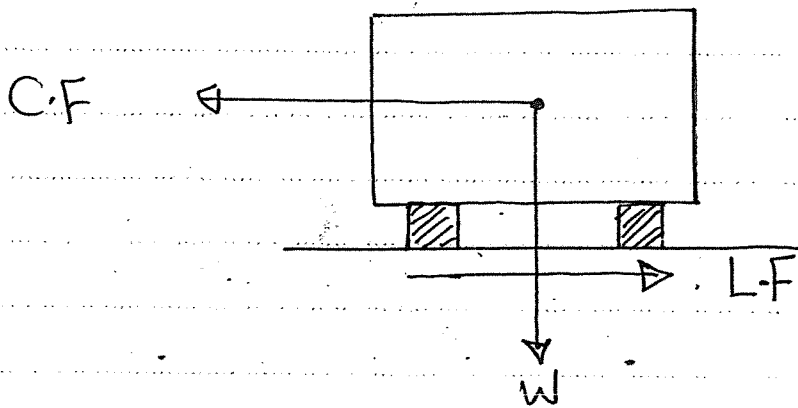
# Properties of Circular Curves

- length of Curve  $L_c = R * \Delta_{\text{Rad}}$
- Tangent  $T = R * \tan\left(\frac{\Delta}{2}\right)$
- Chord الوتر  $C = 2R * \sin\left(\frac{\Delta}{2}\right)$
- Mid ordinate  $M = R - R * \cos\left(\frac{\Delta}{2}\right)$
- External Distance  $E = R * \sec\left(\frac{\Delta}{2}\right) - R$   
 $= \frac{R}{\cos\left(\frac{\Delta}{2}\right)} - R$

## Forces Acting on Circular Curve

A vehicle moving on a circular curve will be influenced by centrifugal force.

عند سير المركبات على المنحنيات الأفقية فإنه تتولد قوة طاردة مركزية قد تسبب في انزلاق المركبة وأحياناً خروجها من المنحنى



$$C.F = \frac{W * U^2}{g * R} \quad (\text{centrifugal force})$$

(But) This force is resisted by lateral friction  
(إعاقة الاحتكاك الجانبي)

$$L.F = W * f$$

(For Stability) ولتصل الأجزاء

$$L.F = C.F$$

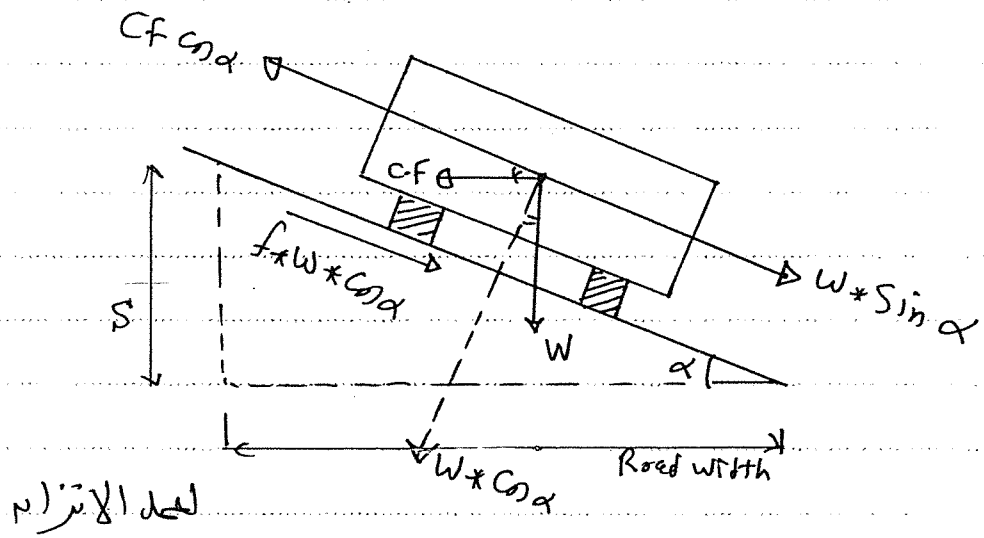
$$W * f = \frac{W * U^2}{g * R}$$

$$\therefore f = \frac{U^2}{g * R}$$

$V \rightarrow \text{km/hr}$        $g = 9.81 \text{ m/s}^2$       بأخذ  $g = 9.81 \text{ m/s}^2$

$$f = \frac{(V/3.6)^2}{9.81 * R} = \frac{V^2}{127 R}$$

حيث (f) هو معامل الاحتكاك الجانبي  
ولكن في معظم الإحصاءات تكون قوة الإدراك المركزي  
أكبر من مقاومة الاحتكاك الجانبي ولهذا نلجأ  
إلى عمل رفع القصر عن البنية



$$W \sin \alpha + f \times W \cos \alpha = CF \times \cos \alpha$$

$$\cancel{W} \sin \alpha + f \times \cancel{W} \cos \alpha = \frac{W \times V^2}{g \times R} \times \cos \alpha$$

وبالقسم على  $(\cos \alpha)$

$$\tan \alpha + f = \frac{V^2}{127 R}$$

حيث  $e = \frac{\text{معدل الارتفاع الطرقي من منطقة المنحنى}}{\text{معدل الطرقي}} = \frac{S}{L} = \tan \alpha$

$$e + f = \frac{V^2}{127 R}$$

$$R = \frac{V^2}{127(e+f)}$$

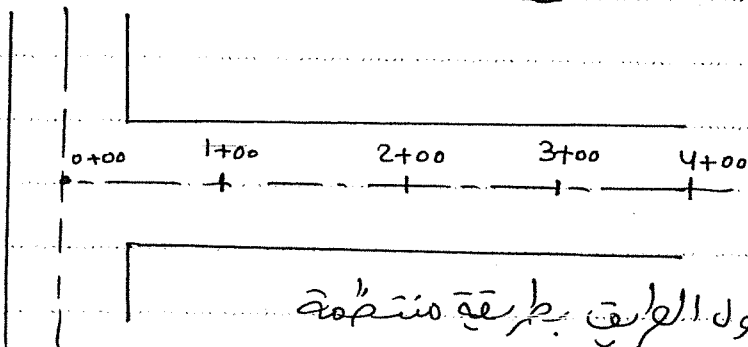


- حساب
- $R \rightarrow$  Radius of circular curve in (m)
  - $v \rightarrow$  design speed in km/hr
  - $e \rightarrow$  Superelevation
  - $f \rightarrow$  coefficient of lateral friction  $(0.1) \rightarrow (0.2)$   
depending on speed - typically  $0.14 \rightarrow 0.16$

إذا لم تكن (e) ممتعة البنية فإرتنا لا نحتاج إلى تعويض  
Superelevation حيث أن قوة الاحتكاك الجانبية من هذه الحالة  
ومما تلحقها قوة القوة المركزية.

- Highest in common use = 10%. For (e) Superelevation.
- 12% with no ice and snow on low volume gravel-surfaced roads.
- 8% is the logical maximum to minimize slipping by stopped vehicles.

# المحطات Stations



المحطات :- هي تقسيمات لطول الطريق بطريقة منتظمة  
 بغرض تسهيل توقيعة من الطبيعة .  
 فمثلاً عندما يركب توقيع نقطة 4+10 مثلاً نذهب عند محطة رقم 4+00  
 ثم نقيس 10 متر بعد ما

ما معنى محطة رقم 4+10

أيضا ان الاجابة سوف على  
 قيمة المحطة

فلو قال ان المحطة  $1 Sta = 100 m$  فده معناه ان النقطة  
 المفهورة تبعد مسافة (4) محطات يعني 400 متر + 10 متر  
 ان ان النقطة تبعد 410 متر من بداية الطريق

ولو قال ان المساحة  $1 Sta = 30 m$  فدها يعني ان  
 النقطة المفهورة تبعد مسافة (4) محطات يعني  
 $4 * 30 = 120$  متر + 10 متر ان ان النقطة  
 تبعد مسافة 130 متر من بداية الطريق

عندما نقول (4+10)

وده يعني كسر محطة  
 وعارة لا يزيد عن قيمة  
 المحطة  
 ويكون بالمتر  
 الرقم ده يعني محطة

(Ex)

Road with horizontal Curve having an external angle of  $22^{\circ}30'$  & degree of the Curve =  $2.5^{\circ}$

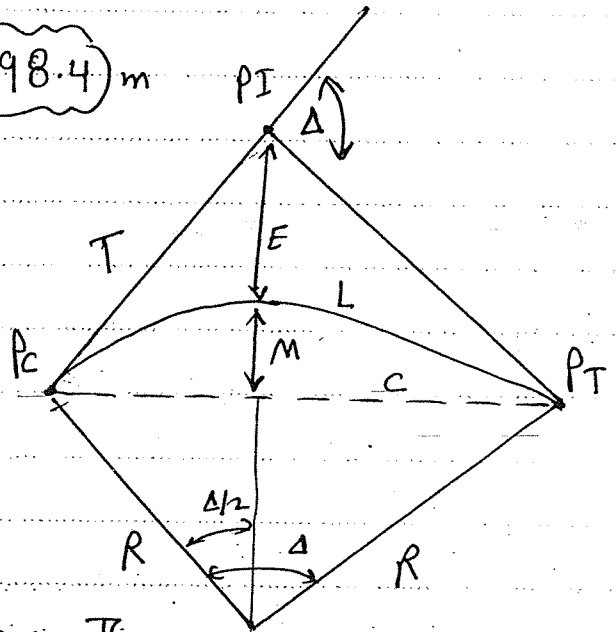
(PI) Station =  $175+50$  , Station =  $100$  m

estimate the Station of  $P_c$  &  $P_T$   
then find  $E, M, C$

$$\rightarrow R = \frac{1746}{D^{\circ}} = \frac{1746}{2.5} = \boxed{698.4} \text{ m}$$

$$\rightarrow \tan \frac{\Delta}{2} = \frac{T}{R}$$

$$\begin{aligned} T &= R \times \tan\left(\frac{\Delta}{2}\right) \\ &= 698.4 \times \tan\left(\frac{22.5}{2}\right) \\ &= \boxed{138.9} \text{ m} \end{aligned}$$



$$\begin{aligned} \rightarrow L_c &= R \times \Delta_{\text{Rad}} = 698.4 \times 22.5 \times \frac{\pi}{180} \\ &= \boxed{274.26} \text{ m} \end{aligned}$$

$$= (2 + 74.26)$$

→ Station of  $P_c$

$$\begin{aligned} \text{St}(PI) - T &= (175+50) - (138.9) \\ &= (174+11.1) \end{aligned}$$

→ Station of  $P_T$

$$\begin{aligned} \text{St}(P_c) + L_c &= (174+11.1) + (2+74.26) \\ &= (176+85.36) \end{aligned}$$

$$C = 2 * R * \sin \frac{\Delta}{2} = 2 * 698.4 * \sin \frac{22.5}{2}$$

$$= 272.5 \text{ m}$$

$$M = R - R * \cos \left( \frac{\Delta}{2} \right) = 698.4 \left( 1 - \cos \frac{22.5}{2} \right) = 13.4 \text{ m}$$

$$E = R * \sec \left( \frac{\Delta}{2} \right) - R = \frac{698.4}{\cos \frac{22.5}{2}} - 698.4 = 13.7 \text{ m}$$

Ex

For a maximum superelevation of 0.1, compute the max degree of curve for design speeds of 50, 60, 70, 80 and 100 km/hr. Using the following values for side friction.

Design speed km/hr	50	60	70	80	100
max safe side friction	0.16	0.15	0.14	0.13	0.12

\* Sol \*

$$e + f = \frac{V^2}{127 R} \rightarrow R = \frac{V^2}{127 * (e + f)}$$

$$D^\circ = \frac{1746}{R}, \quad e = 0.1 \quad \text{given}$$

V (km/hr)	50	60	70	80	100
e + f, e = 0.1	0.26	0.25	0.24	0.23	0.22
$R = \frac{V^2}{127 * (e + f)}$	75.71	113.38	160.76	219.1	357.91
$D^\circ = \frac{1746}{R}$	23.06°	15.4°	10.86°	7.97°	4.88°

# EX

Vehicles performance is being tested on a large flat area. for this situation :-

① → What coefficient of side friction must be developed to speed of 100 km/hr. ( $D=10^\circ$ )

② → What is the sharpest curve (stated in degree) that the vehicle travelling 100 km/hr can travel if the coefficient of side friction is 0.4?

\* SOL \*

① at  $v=100$  km/hr,  $D=10^\circ$ ,  $f=??$

$$R_c = \frac{1746}{D^\circ} = \frac{1746}{10} = \boxed{174.6} \text{ m}$$

$$\therefore f = \frac{U^2}{127R} = \frac{(100)^2}{127 \times 174.6} = \boxed{0.451}$$

② at  $v=100$  km/hr,  $f=0.4$ ,  $D=??$

$$f = \frac{U^2}{127R} \Rightarrow 0.4 = \frac{(100)^2}{127 \times R}$$

$$R = 196.89 \text{ m}$$

$$\therefore R = 196.89 = \frac{1746}{D}$$

$$D = \boxed{8.87}^\circ$$

## Ex

An existing horizontal curve on a highway has a radius of 150 m, which restricts the posted speed limit on this section of the road to only 59% of the design speed of the highway. If the curve is to be improved so that its posted speed will be the design speed of the highway, determine the minimum radius of the new curve. Assume that the rate of superelevation is 0.08 for both the existing curve and the new curve to be designed and the coefficient of lateral friction is 0.14.

Sol.

Determination of existing speed

$$R = \frac{V^2}{127(e+f)} \quad 150 = \frac{V^2}{127(0.08 + 0.14)}$$

$$V = 64.73 \text{ km/hr}$$

Design Speed

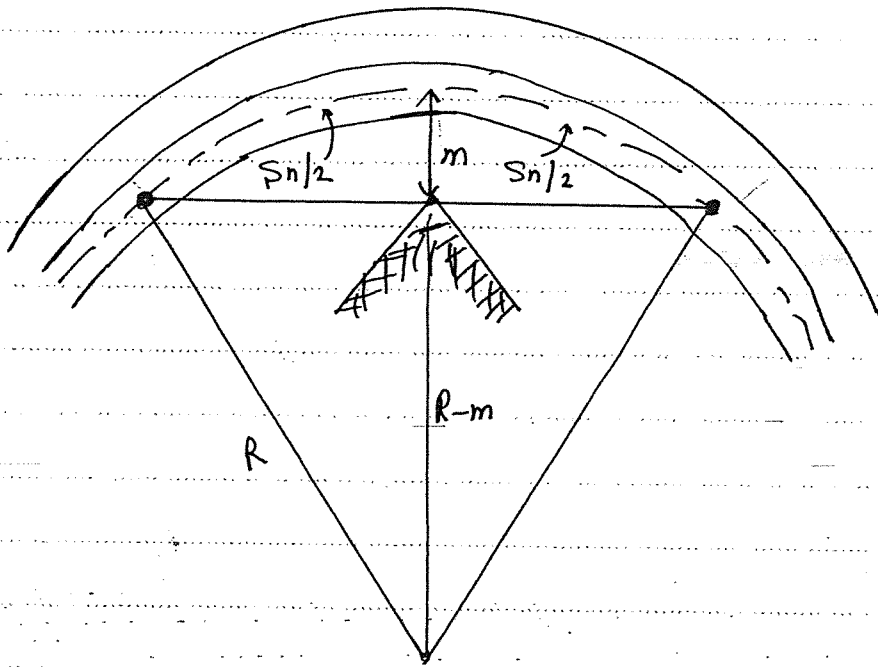
$$V = \frac{64.73}{0.59} = 110 \text{ km/hr}$$

New Radius

$$R = \frac{(110)^2}{127(0.08 + 0.14)} = 433 \text{ m}$$

# Sight Distance of Horizontal Curve

عن مسووع التخم على المنصية الأفقية لذلك فإن  
المسافة المطلوبة الواحد على المنصية الأفقية  $S_n$



$$\left(\frac{S_n}{2}\right)^2 = m^2 + (R^2 - (R-m)^2)$$

$$= \cancel{m^2} + R^2 - \cancel{R^2} + 2Rm - \cancel{m^2}$$

$$\left(\frac{S_n}{2}\right)^2 = 2Rm$$

$$S_n = \sqrt{8mR}$$

$(S_n)$  → Stopping Sight distance

$(m)$  → the lateral distance at the height of the driver's eyes.

$(R)$  → the radius at the center of the inner lane.

# EX

A corner of an existing obstruction is 6m from C.L on 12 degree curved portion of 2 lane roadway having a lane width of 3m :-

what is the horizontal sight distance along the centerline of the inside lane & what is the safe operating speed

SOL.

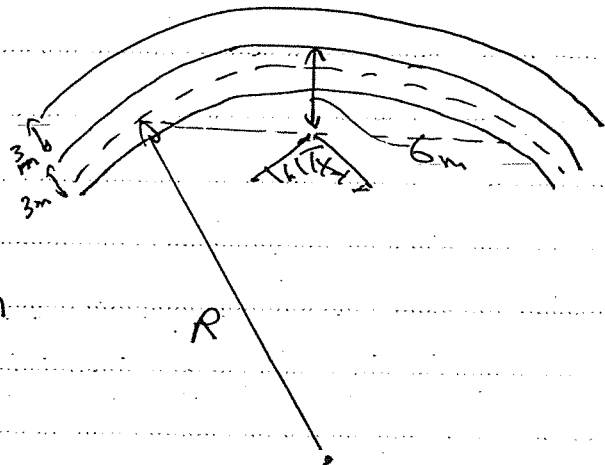
$$R_c = \frac{1746}{D^\circ} = \frac{1746}{12} = 145.5 \text{ m}$$

$$m = 6 - \frac{3}{2} = 4.5 \text{ m}$$

$$R = 145.5 - \frac{3}{2} = 144 \text{ m}$$

$$S_n = \sqrt{8mR} =$$

$$\sqrt{8 \times 4.5 \times 144} = 72 \text{ m}$$

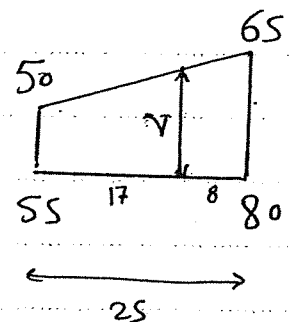


From table # 4 Data Sheet

$$V_{max} = \frac{50 \times 8 + 65 \times 17}{25}$$

$$= (60.2) \text{ km/hr}$$

dlc → yL





If the desired operating speed is 100 km/hr  
how far the obstruction should be set back to  
satisfy the stopping sight distance.

from table (4)

@  $v = 100$  km/hr

$$S_n = \frac{150 + 165}{2} = 157.5 \text{ m}$$

$$S_n = \sqrt{8mR}$$

$$\therefore m = \frac{S_n^2}{8 \times R} = \frac{(157.5)^2}{8 \times 144} = 21.53 \text{ m}$$

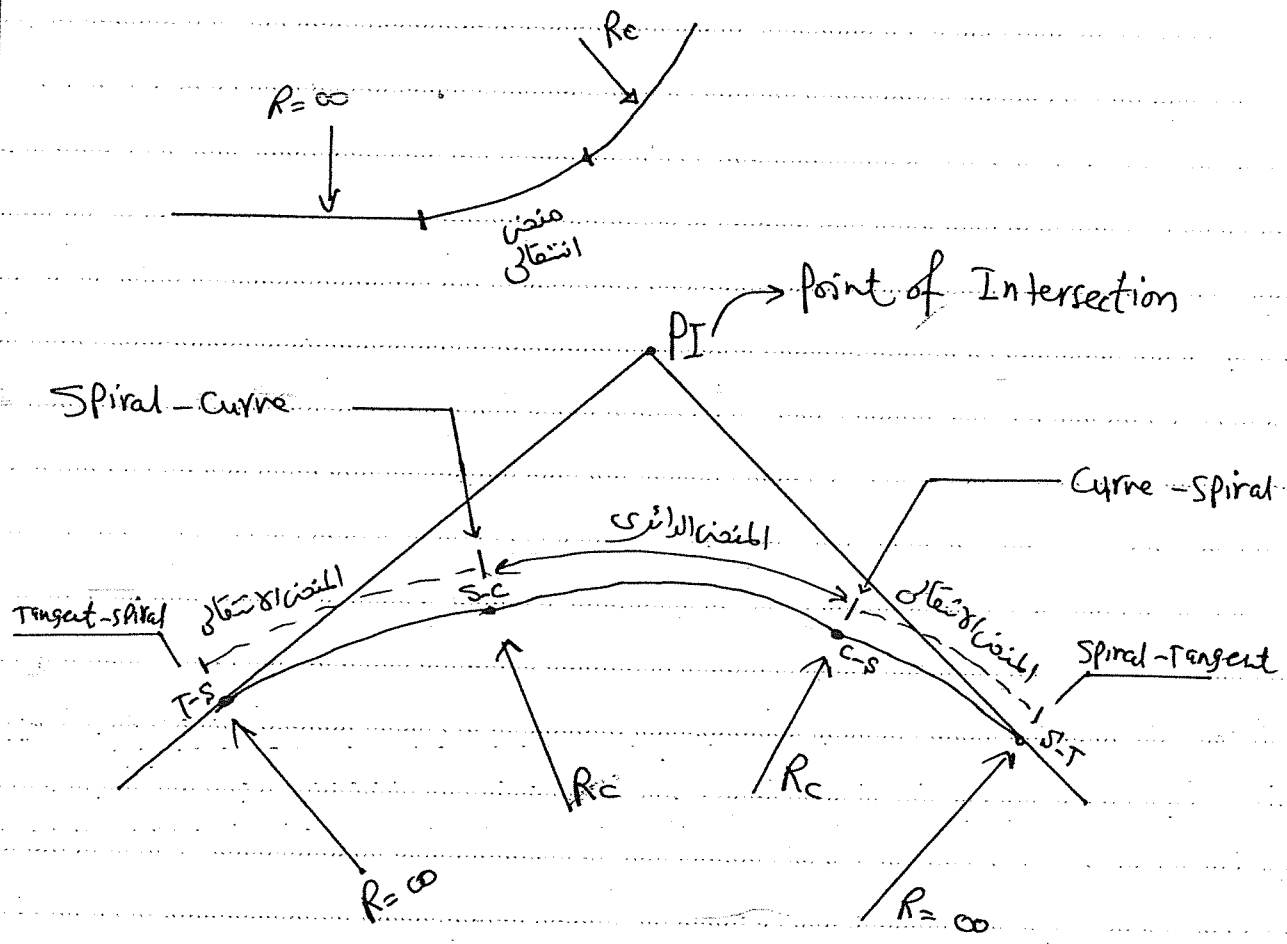
$$\therefore \text{obstruction distance} = 21.53 + 1.5 = 23.03 \text{ m}$$

23.03 m ←

# Transition Curve (Spiral Curve)

## المنحنى الانتقالي

هو منحنى نصف قطره يتغير تدريجياً



## الفرض من استخدام المنحنى الانتقالي

- ① لتغلب التغيير المفاجئ من الحركة على خط مستقيم إلى الحركة على المنحنى اللانثري وبالتالي يحفظ السائق بالسير في تارته .
- ② الشعور تدريجياً بالقوة الطاردة المركزية للمنحنى .
- ③ تنفيذ ارتفاع القمم عن البطن Super elevation تدريجياً فلاحة .
- ④ تنفيذ توسيع الطريق تدريجياً فلاحة .

- Transition Curves are placed between tangents and circular curves.
- The transition curve provides the following :-
  - \* A vehicle path that gradually increases or decreases the radial force.
  - \* Gradual change in curvature - starts with zero at tangent and ends with a curvature  $D$  at circular curve.
  - \* Gradual introduction of super-elevation.
  - \* " " " " " lane widening.
- Euler Spiral Curve is the most widely used.
- An Euler spiral is a curve whose curvature changes linearly with its curve length.

## Length of Spiral Curve :-

طول المنحنى الإنتقالي

The maximum of the following

$$\textcircled{1} L_s = \frac{A^2}{R_c}$$

(A) data sheet table (9)

دالة  $A$  على السرعة

Where (A) is the curve constant [function of speed] and  $R_c$  is the radius of the horizontal curve.

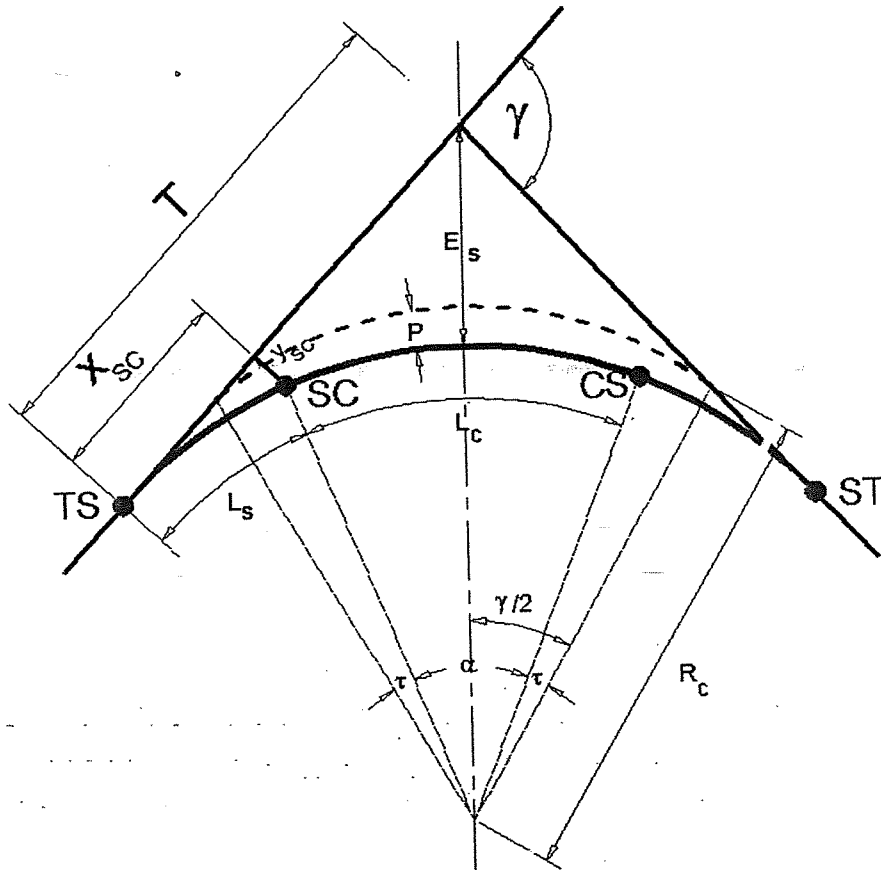
$$\textcircled{2} L_s = \frac{V^3}{28 * R_c}$$

( $N_c$ ) km/hr	40	60	80	100	120	140
Amin	50	100	150	200	350	500

$$\textcircled{3} L_s = 50 \text{ m}$$



Elements of circular and transition curves



- $L_s = 2\tau_{rad} \times R_c$
- $\gamma^{\circ} = 2\tau^{\circ} + \alpha^{\circ}$
- $L_c = \alpha_{rad} \times R_c$
- $P = Y_{sc} + R_c \times [\cos\tau^{\circ} - 1]$
- $T = X_{sc} + [P + R_c] \times \tan\left(\frac{\gamma^{\circ}}{2}\right) - R_c \times \sin\tau$
- $E_s = [P + R_c] \times \sec\left(\frac{\gamma^{\circ}}{2}\right) - R_c$

Coordinates of transition curve:

$$X = L \times \left[1 - \frac{L^3}{40 \times A^3}\right]$$

$$Y = \frac{L^3}{6A^2} \times \left[1 - \frac{L^4}{56 \times A^4}\right]$$

# ولتوقيع المنحنيات الأفقية : بالنسبة للجزء الدائري

① Find  $\tau$

$$L_s = 2 * \tau_{rad} * R_c \Rightarrow \tau = \sqrt{R_{ad}} = \sqrt{}$$

② Find  $\alpha$

$$\gamma^\circ = 2\tau^\circ + \alpha^\circ \Rightarrow \alpha = \sqrt{}$$

③ Find  $P$

$$P = y_{\text{spiral curve}} + R_c * (\cos \tau^\circ - 1)$$

④ Find  $(L_c, T, E_s)$

$$\bullet L_c = \alpha_{rad} * R_c, \quad \alpha_{rad} = \alpha^\circ * \frac{\pi}{180}$$

$$\bullet T = X_{s.c} + (P + R_c) * \tan\left(\frac{\gamma^\circ}{2}\right) - R_c * \sin \tau$$

$$\bullet E_s = (P + R_c) * \sec\left(\frac{\gamma^\circ}{2}\right) - R_c$$

$$= (P + R_c) * \frac{1}{\cos\left(\frac{\gamma^\circ}{2}\right)} - R_c$$

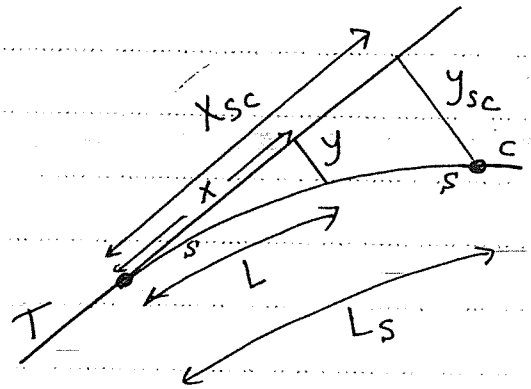
وبالنسبة للمحور الانتقالي :-

حساب اى احاديث (y) مقابل اى مائة (X) مائة

على المحاور نفوض في المعادلات

$$X = L * \left( 1 - \frac{L^4}{40 * A^4} \right)$$

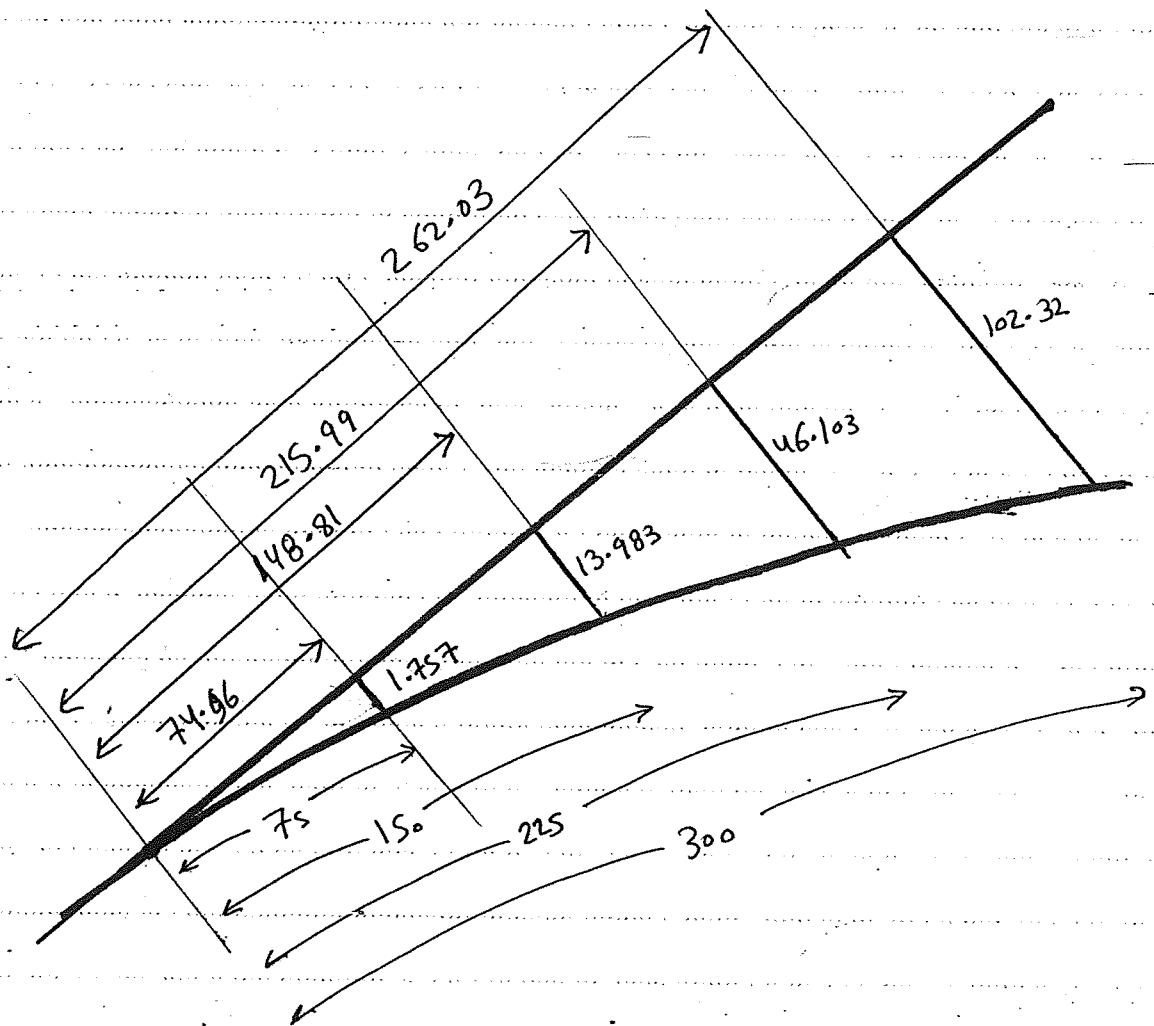
$$y = \frac{L^3}{6A^2} * \left( 1 - \frac{L^4}{56 * A^4} \right)$$



Ex

Calculate four coordinates on a spiral curve which length is 300 m long and  $A = 200$

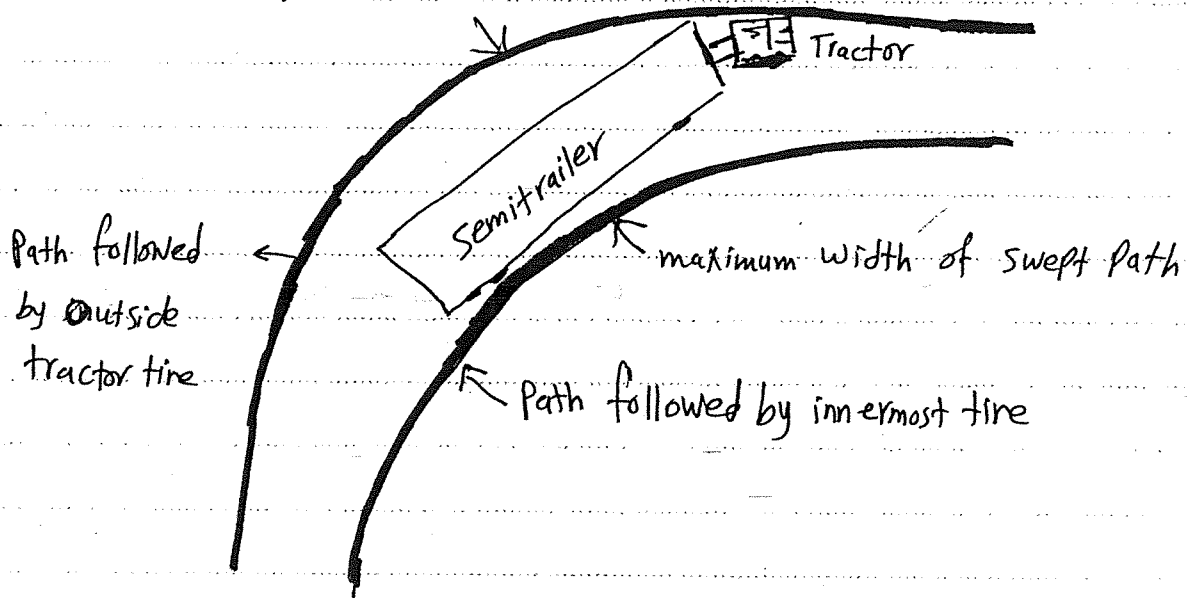
L	$\frac{1}{4}L_s = 75$	$\frac{1}{2}L_s = 150$	$\frac{3}{4}L_s = 225$	$L_s = 300$
$X = Lx \left[ 1 - \frac{L^4}{40A^4} \right]$	74.96	148.81	215.99	262.03
$y = \frac{L^3}{6A^2} * \left[ 1 - \frac{L^4}{56A^4} \right]$	1.757	13.983	46.103	102.32



# Widening of Horizontal Curve

Widening is carried out because :-

- Rear wheels do not follow the path front wheels
- Drivers tend to weave towards the center of the curve



• هو تزويد عرض الطريق خلال المنحنى

• منع التوسع خلال المنحنيات الأفقية للزوايا الأسيية

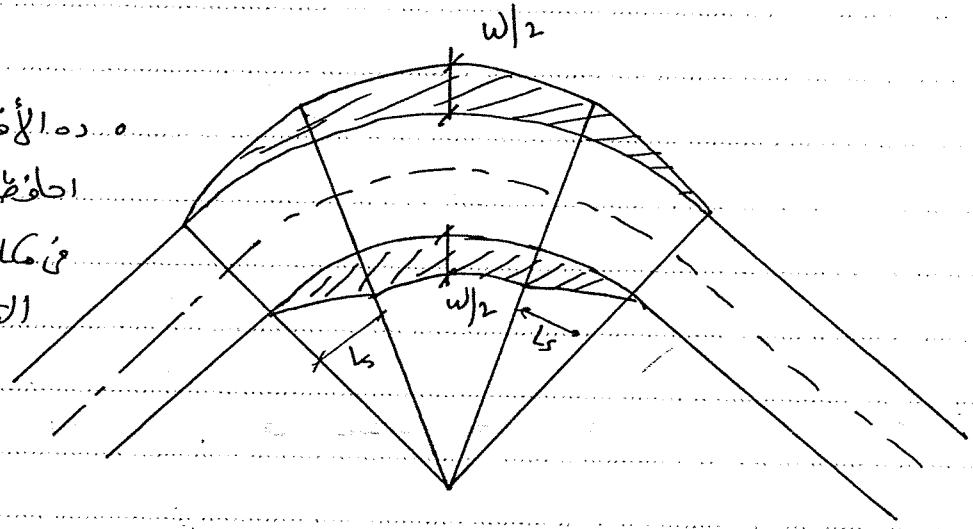
- ① العجلة الخلفية لا تتبع حركة العجلة الأمامية في المنحنيات
- ② ميل السائقين إلى الابتعاد عن الكافة الداخلية للطريق



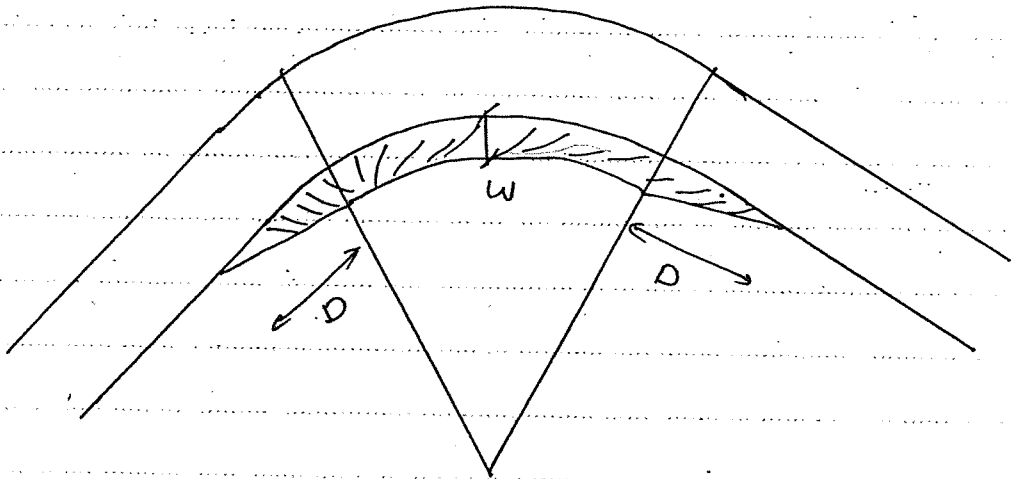
# طرق تنفيذ التوسيع :-

① في حالة وجود منحني انتقال (توسعه من اتجاهين)

هـ - ده - الأفضل حيث كلما  
اطول على كانه (C-1)  
في مكانه كانه أفضل من  
التنفيذ



② في حالة عدم وجود منحني انتقال (توسعه من ناحية واحدة)



$$\text{Widening } (W) = W_1 + W_2$$

- $(W_1)$  → is the widening needed due to wheels shift  
توسيع لعمق انطباق العجلات مع المسار
- $(n)$  → is the number of lanes.  
عدد المسارات
- $(R_c)$  → the Radius of the horizontal Curve.  
نصف قطر المنحنى الأفقي
- $(L)$  → the length of the design Vehicle.  
طول المركبة التصميمية

$$W_1 = n * (R_c - \sqrt{R_c^2 - L^2})$$

$$W_2 = \frac{0.105 V}{\sqrt{R_c}}$$

- $(W_2)$  → is the widening needed due for Driver perception  
توسيع لمراقبة السائق
- $(V)$  → The design speed.

$$\text{Widening } (W) = n * (R_c - \sqrt{R_c^2 - L^2}) + \frac{0.105 V}{\sqrt{R_c}}$$

# EX

A two lane of 3.75 m traffic lane width, goes around a 8 degree curve, for a design speed of 100 km/hr it is required:-

- ①. Compute the extra width required at the curve.
- ②. Compute the minimum length of transition curve.
- ③. Draw plan showing the development of widening.

L vehicle = 6 m

1. Widening  $w = ?$

$$R_c = \frac{1746}{D^\circ} = \frac{1746}{8} = 218.25 \text{ m}$$

$$W = 2 \times \left( R_c - \sqrt{R_c^2 - L^2} \right) + \frac{0.105 V}{\sqrt{R_c}}$$
$$= 2 \times \left( 218.25 - \sqrt{218.25^2 - 6^2} \right) + \frac{0.105 \times 100}{\sqrt{218.25}}$$
$$= 0.88 \text{ m} \approx 0.9 \text{ m}$$

2. transition curve length  $\rightarrow$

$$① L_s = \frac{A^2}{R_c} = \frac{(200)^2}{218.25} = 183.28 \text{ m} \quad \text{For } V=100 \quad (A=200)$$

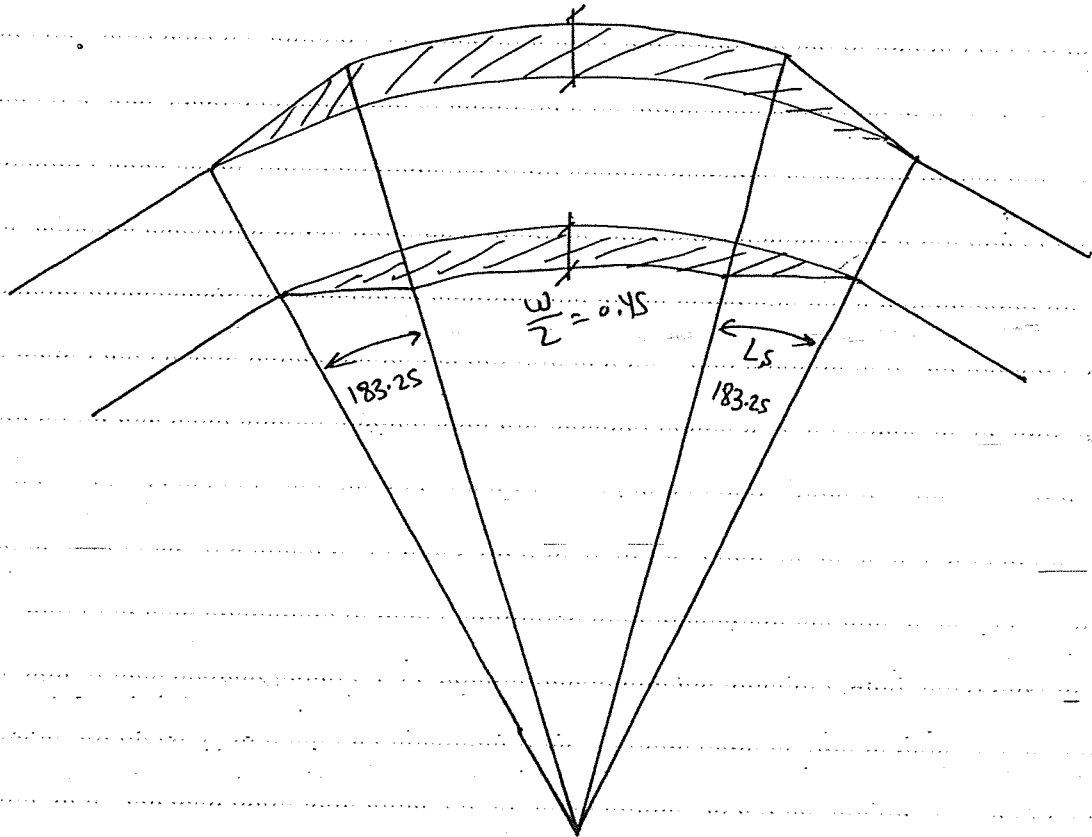
$$② L_s = \frac{V^3}{28 \times R_c} = \frac{(100)^3}{28 \times 218.25} = 163.64 \text{ m}$$

$$③ L_{s \text{ min}} = 50 \text{ m}$$

$$(L_s) = 183.28 \text{ m}$$

يوجد منحنى انتقال ← يتم تنفيذ التوسيع على الجانبين

$$w/2 = 0.45$$

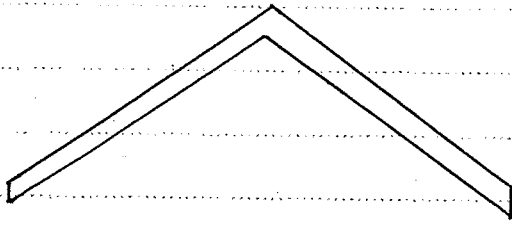


## Home work

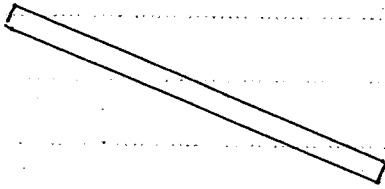
Draw a neat sketch showing the development about the inner edge of 2-lane, 3.75 m, lane width,  $D = 10^\circ$ , cross slope 3:1, long slope = 4%,  $V = 85$  km/hr,  $f = 0.16$ , compute four coordinates on spiral curve if  $\delta = 85^\circ$   
 $A = 200$ , Draw sketches to show the application on extra widening.

حيث  
يوجد أنواع للطرق طبقاً للقطاع العرضي

• Types of Roads according to their cross sections



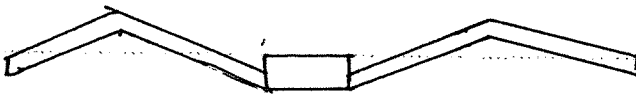
Crowned undivided ✓



Planar undivided



Divided planar with median

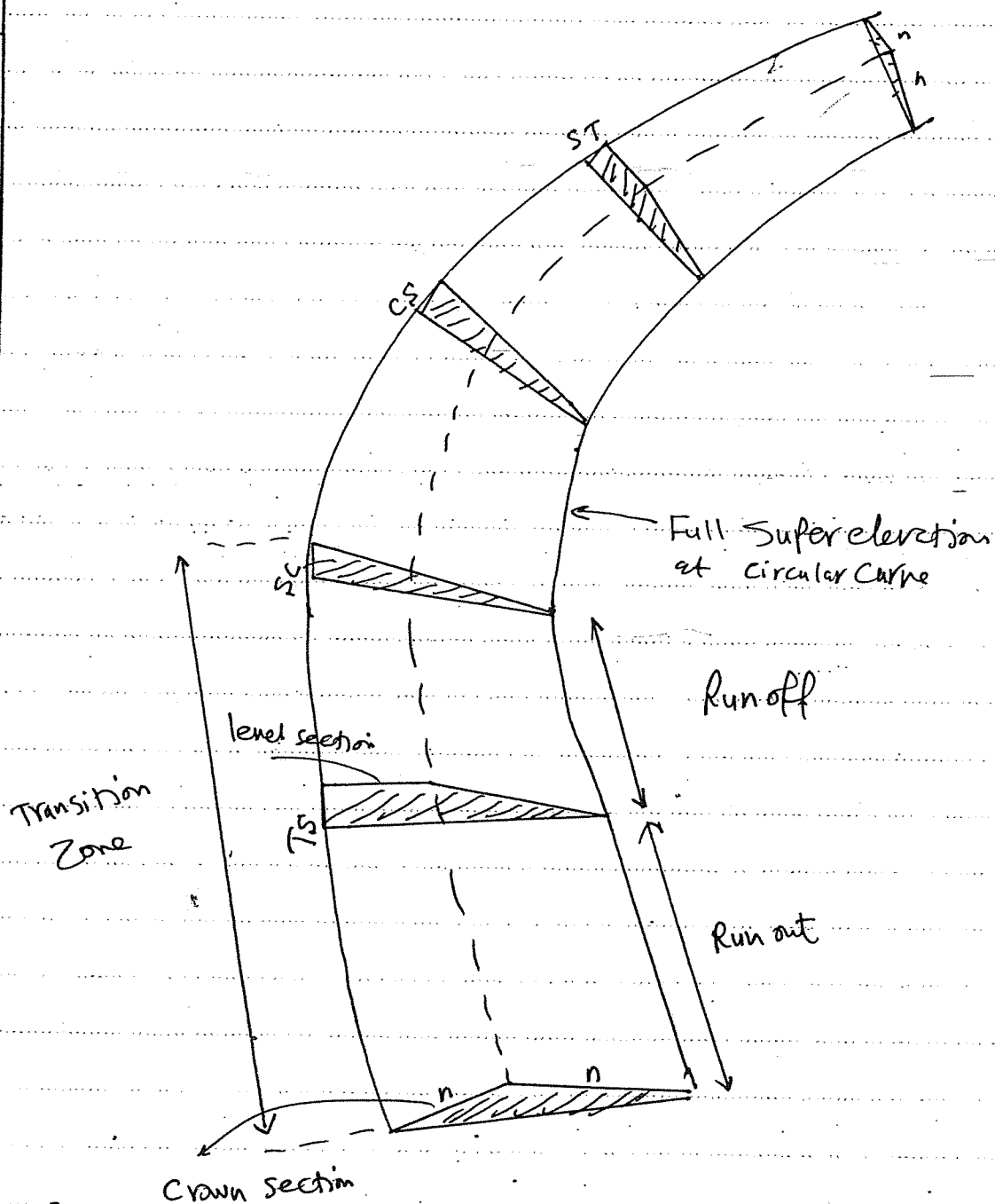


Divided crowned with median

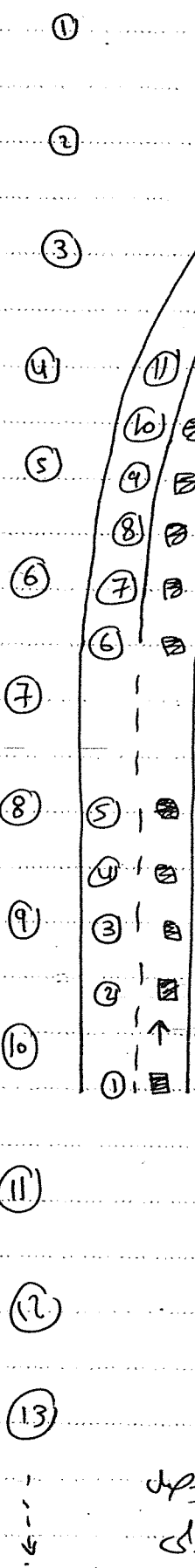
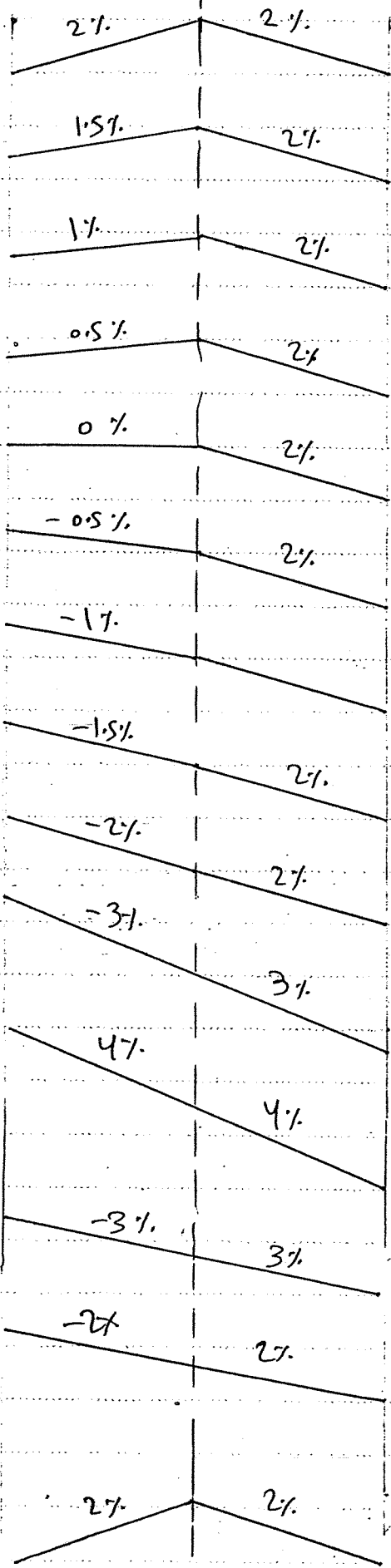
# خطوات تنفيذ ال Super elevation

## Rotation about centerline

بدراسة القطاع العرضي للطريق حول المحور الطولي



c.l

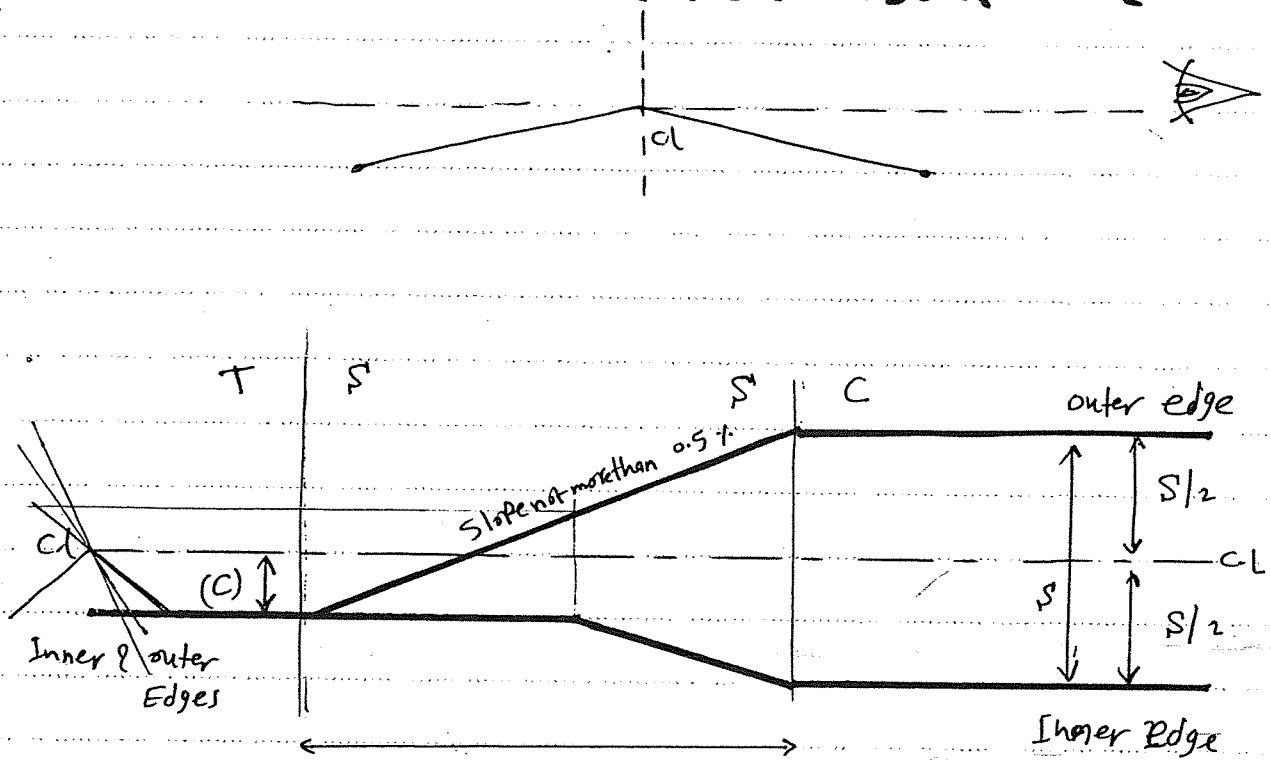


Plan

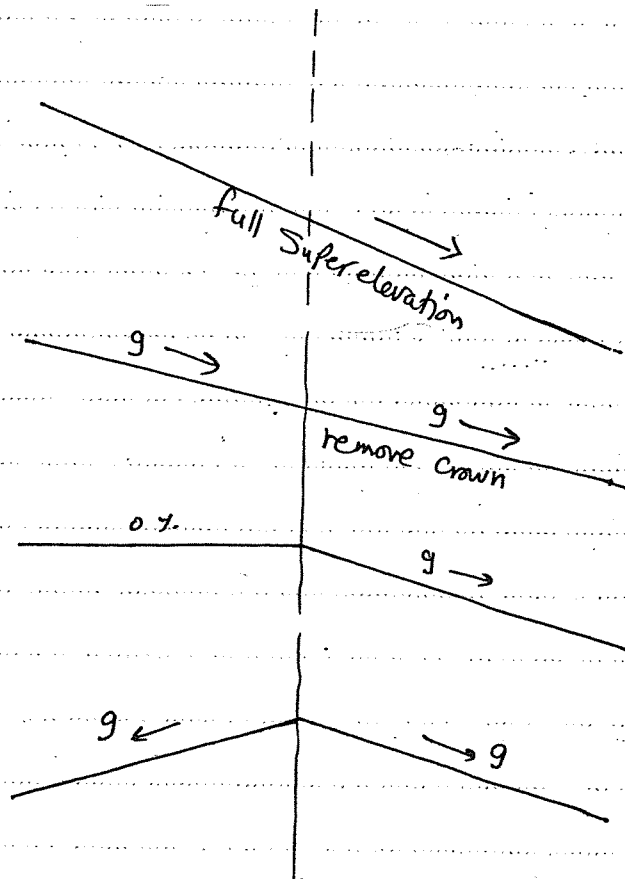
تم تغيير الميل إلى اسرعه  
للكارح والى



# (a) Transition Curve Rotation about C.L

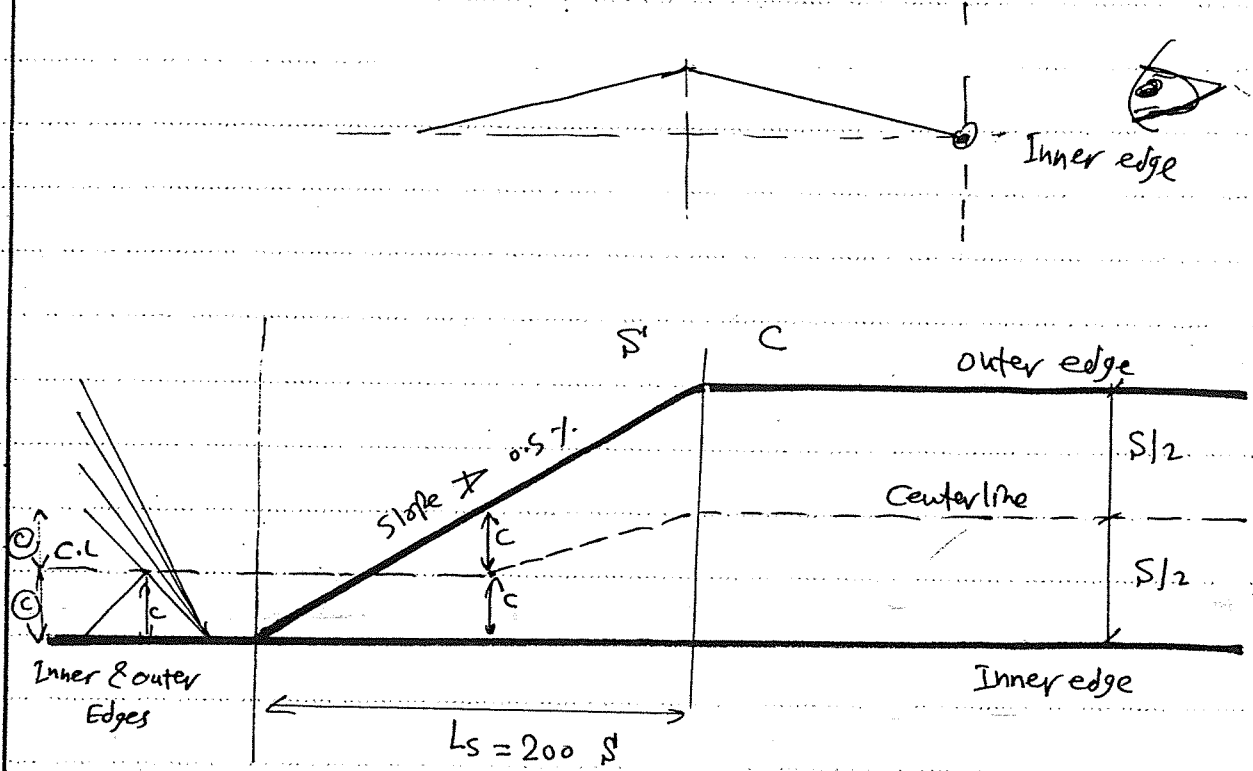


$$L_s = 200 \times \left( \frac{S}{2} + c \right)$$

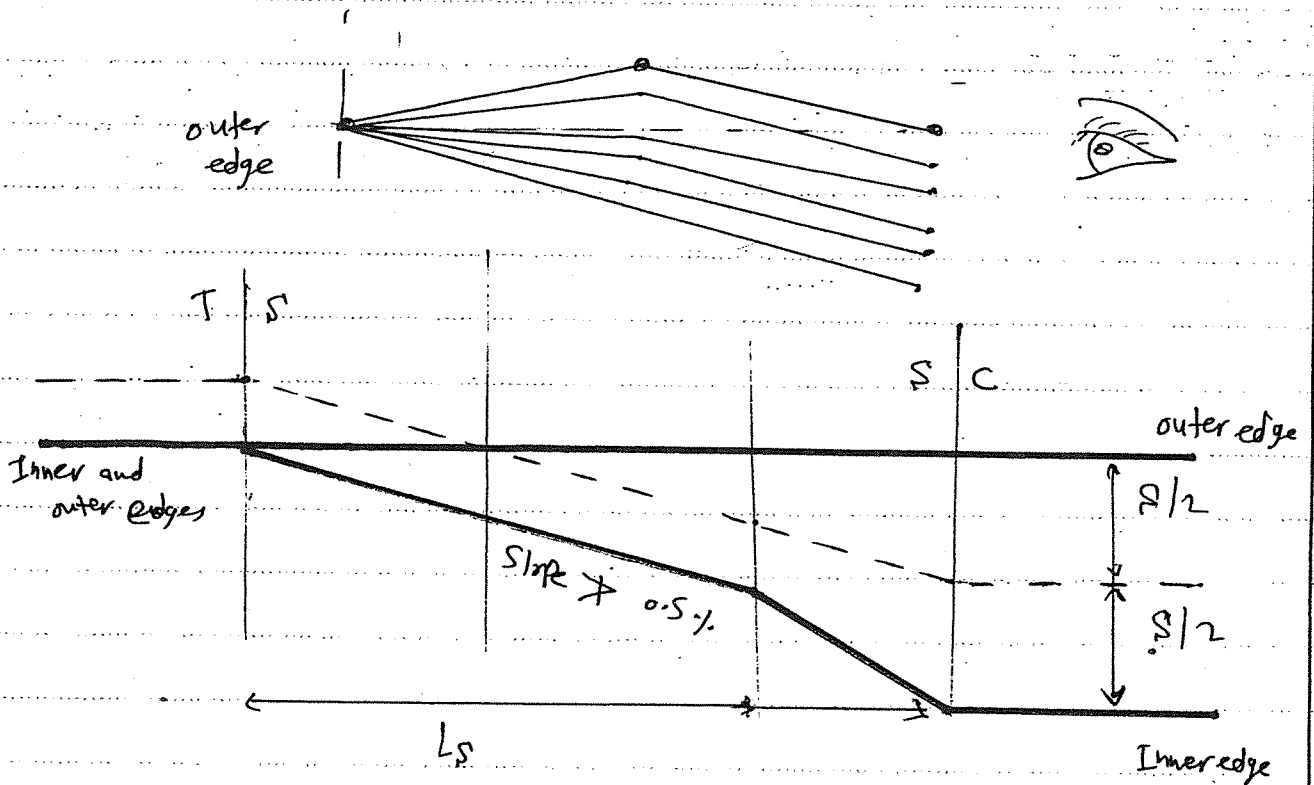




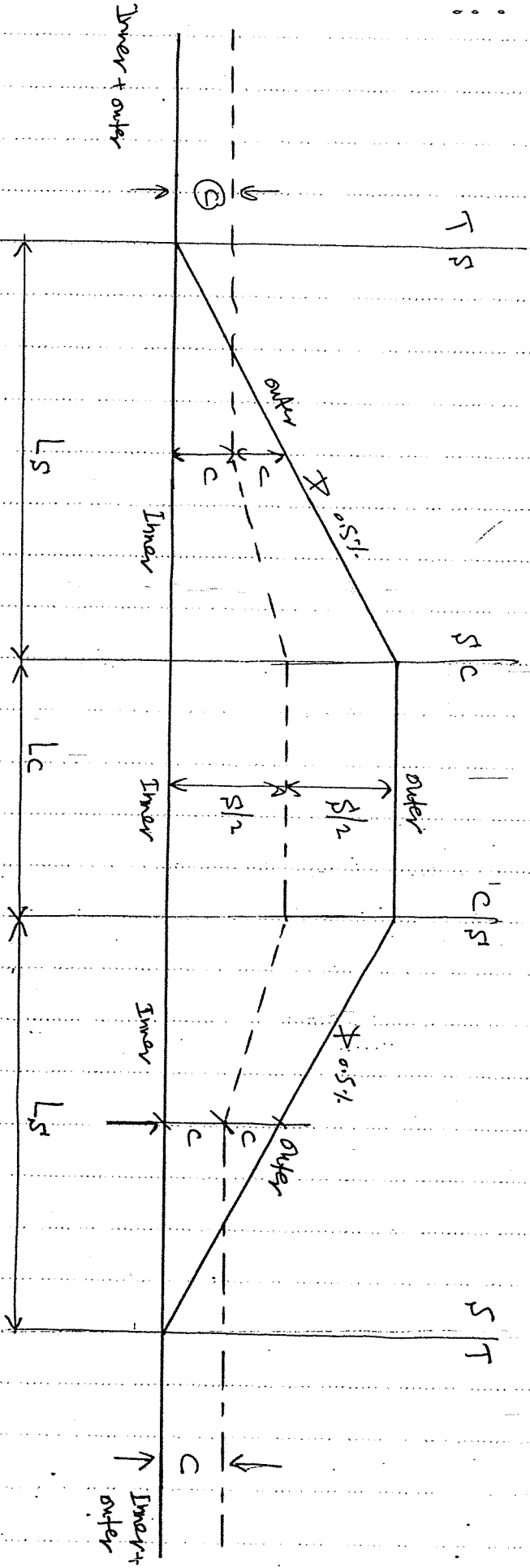
### (B) Transition Curve Rotation about Inner edge



### (C) Transition Curve Rotation about outer edge



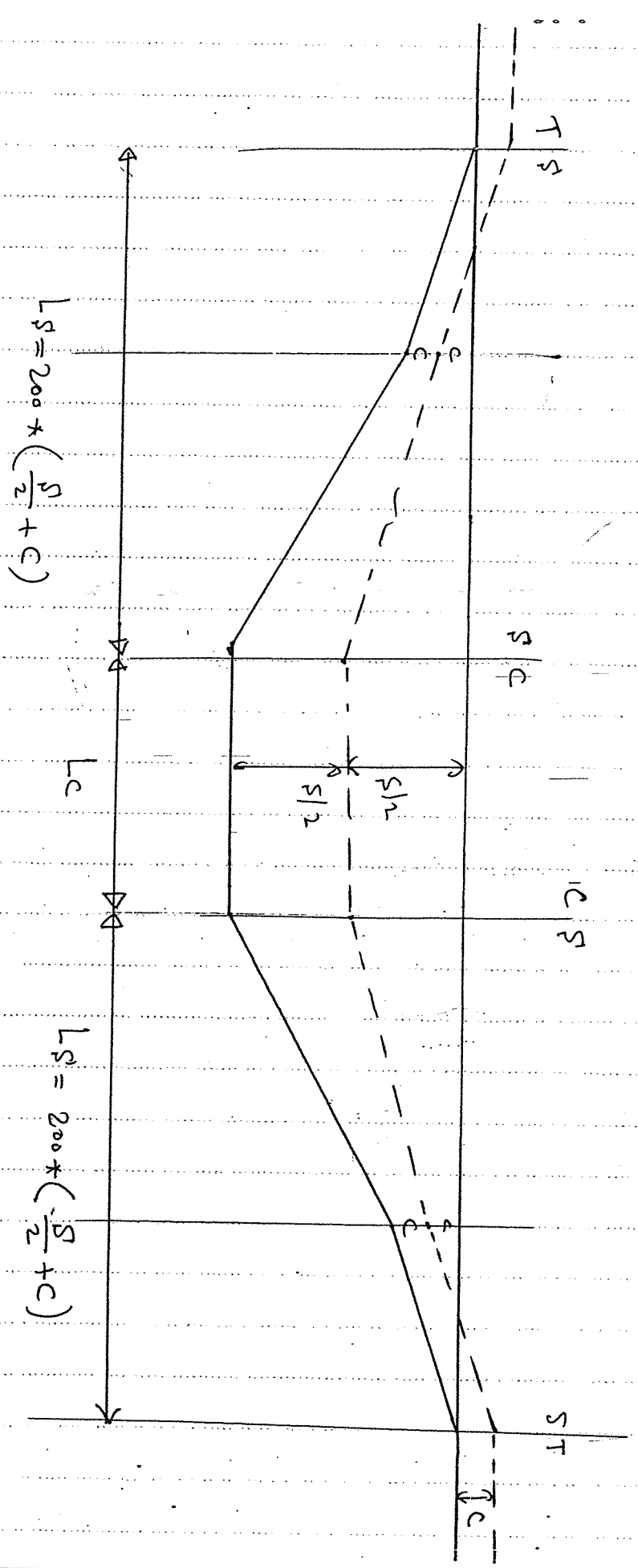
المرحلة الثالثة لتثبيت ال (LS) Super elevation  
 Transition Curve Rotation about Inner Edge  
 حول المرحلة الثالثة لتثبيت ال (LS) Super elevation  
 Transition Curve Rotation about Inner Edge



①  $L_s = \frac{A^2}{Rc}$   
 ②  $L_s = \frac{V^3}{28 Rc}$

- ③  $L_{smin} = 50 \text{ m}$   
 ④  $L_s = 200 * S$   
 (LS) the max of

Transition Curve Relation about outer edge  
 (LS) به سوا ارتفاع القطار  
 Super elevation  
 حركه كماله لتنفيد  
 حركه الكانه الكافيه (المنح)



## Ex

The centerline of a 2-lane road 7.5 m wide with design speed of 80 km/hr runs along a horizontal curve consisting of a circular curve and two transition curves. The road has a cross slope of 1.5% and longitudinal slope -1%. The tangent spiral point (T.S.) has a station [215+00] and an elevation = 50 m along the centerline. The circular curve has a degree of curve = 8 degree and external angle 80 degree,  $f_s = 0.17$ , station = 100

- ① Determine the length of the transition curve and the length of the circular curve.
- ② Draw a neat sketch showing the attainment of super-elevation along the curve by rotation about the inner edge.
- ③ Calculate the station and elevation of the controlling points of the horizontal curve T.S., S.C., C.S. and S.T. at the centerline as well as the inside and outside edges of the pavement.

$$\textcircled{1} \quad R = \frac{1746}{D^{\circ}} = \frac{1746}{8} = \textcircled{218.25} \text{ m}$$

Superelevation

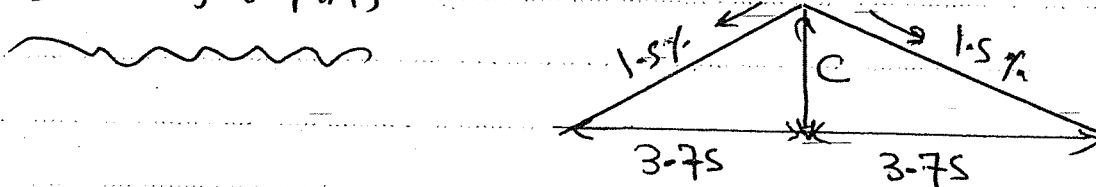
$$e + f_s = \frac{V^2}{127 R_c}$$

$$e + 0.17 = \frac{(80)^2}{127 \times 218.25}$$

$$e = \textcircled{0.06}$$

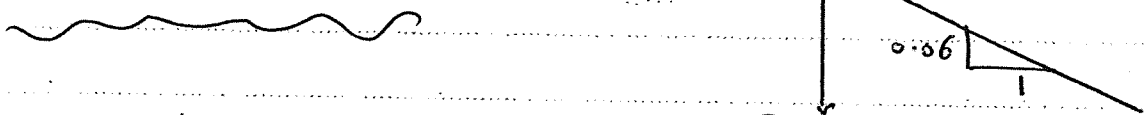
$\textcircled{C}$  11,  $\textcircled{S}$  club

In straight parts



$$C = \left(\frac{7.5}{2}\right) \times 1.5/100 = \textcircled{0.056} \text{ m}$$

In circular parts



$$S = 7.5 + 0.06 = \textcircled{0.45} \text{ m}$$

$\textcircled{L_s}$  the max of

$$\textcircled{1} \quad L_s = \frac{A^2}{R_c} = \frac{(150)^2}{218.25} = \textcircled{103.09} \text{ m}$$

$A = \textcircled{150}$  data sheet

$$\textcircled{2} \quad L_s = \frac{V^3}{28 R_c} = \frac{80^3}{28 \times 218.25} = \textcircled{83.78} \text{ m}$$

$$\textcircled{3} L_s = 50 \text{ m}$$

$$\textcircled{4} L_s = 200 S' = 200 * 0.45 = \textcircled{90} \text{ m}$$

(Rotation about Inner)

$$L_s = \max = \textcircled{103.09} \text{ m}$$

From data sheet

$$* L_s = 2\tau * R_c$$

$$103.09 = 2 * \tau * 218.25$$

$$\tau = 0.2362 \text{ rad} = 0.2362 * \frac{180}{\pi}$$
$$= 13.53^\circ$$

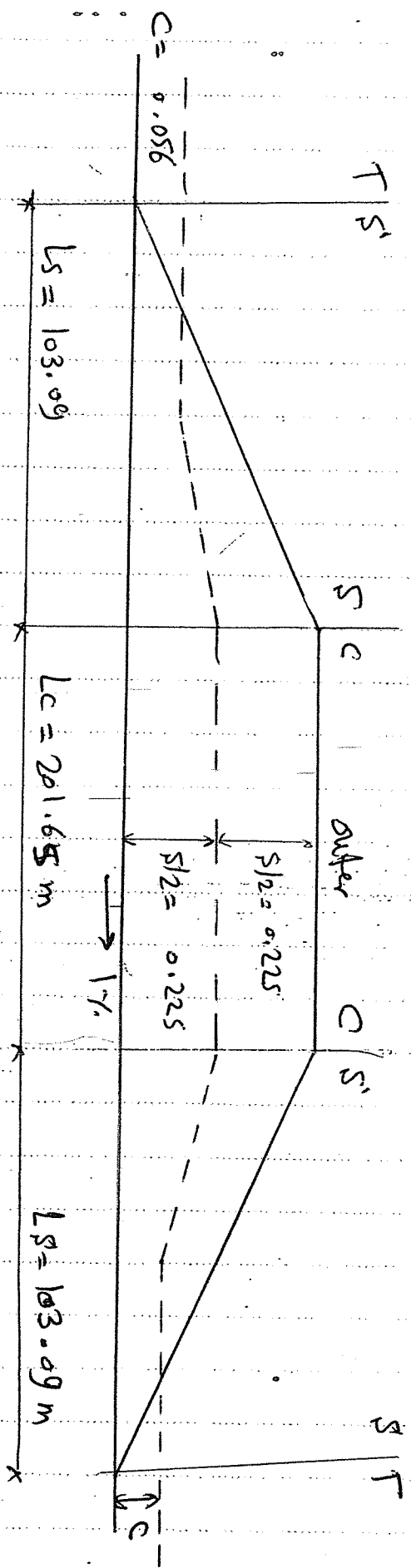
$$* \gamma = 2\tau + \alpha$$

$$80 = 2 * 13.53 + \alpha \quad \alpha = \textcircled{52.94}^\circ$$

$$* L_c = \alpha_{\text{rad}} * R_c$$

$$= 52.94 * \frac{\pi}{180} * 218.25 = \textcircled{201.65} \text{ m}$$





Stations	215+00	216+03.09	218+54.74	219+07.82
Outer	$50 - 0.056 = 49.944$	49.363	47.347	45.866
C.L	50	49.138	47.122	45.922
Inner	49.944	$49.944 - \frac{1}{100} * 103.09 = 48.913$	$48.913 - \frac{1}{100} * 201.65 = 46.897$	$46.897 - \frac{1}{100} * 103.09 = 45.866$

**Elevation**

# EX

A Curved 2-lane road 3.5 m lane width for a design speed of 100 km/hr and superlevation of 0.09 which equals  $\frac{2}{3}$  the coefficient of side friction. It is required

- ① Draw a neat sketch showing the development of superelevation about the centerline if the road cross slope is 2% and longitudinal slope of 2%.
- ② the alignment of horizontal and transition curve if you know that the external angle = 45 degrees. it is required four coordinates.

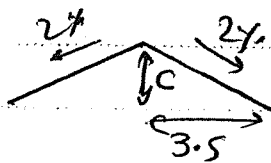
$$e = 0.09 = \frac{2}{3} f_s \quad \rightarrow \quad f_s = \boxed{0.135}$$

$$e + f_s = \frac{V^2}{127 R_c}$$

$$0.09 + 0.135 = \frac{(100)^2}{127 R_c}$$

$$R_c = \boxed{350} \text{ m}$$

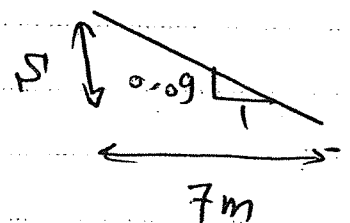
In straight paths



$$C = 3.5 * \frac{2}{100} = 0.07 \text{ m}$$

In circular paths

$$\begin{aligned} S &= 7 * 0.09 \\ &= 0.63 \text{ m} \end{aligned}$$



$(L_s) = \text{the max of}$

$$\textcircled{1} L_s = \frac{A^2}{R_c} = \frac{(200)^2}{350} = \textcircled{114.286} \text{ m}$$

$$\textcircled{2} L_s = \frac{V^3}{28 R_c} = \frac{(100)^3}{28 * 350} = \textcircled{102.04} \text{ m}$$

$$\textcircled{3} L_s = \textcircled{50} \text{ m}$$

$$\textcircled{4} L_s = 200 * \left( \frac{V}{2} + C \right) \quad \text{Rotation about CL}$$

$$= 200 * \left( \frac{0.63}{2} + 0.07 \right) = \textcircled{77} \text{ m}$$

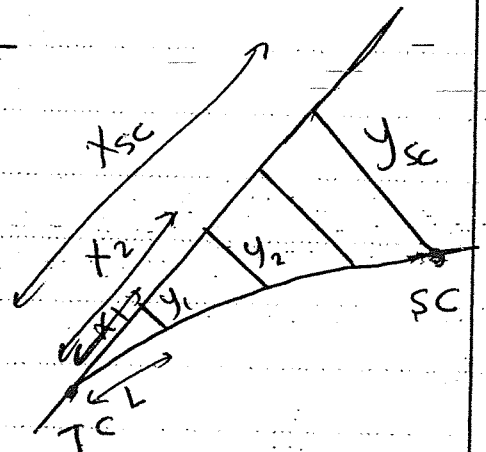
$$L_s = \textcircled{114.28} \text{ m}$$

For transition curve

Required 4 points

$$X = L * \left[ 1 - \frac{L^4}{40 * A^4} \right]$$

$$y = \frac{L^3}{6A^2} * \left( 1 - \frac{L^4}{56 * A^4} \right)$$



L	$\frac{114.286}{4} = 28.57$	57.14	85.71	114.286
X	28.569	57.13	85.637	113.97
y	0.097	0.777	2.621	6.208

for circular curve Data Sheet  $\frac{1}{2}$

① (1)

$$L_s = 2\tau * R_c$$

$$114.28 = 2\tau * 350 \rightarrow \tau = 0.163 \text{ rad}$$

$$= 0.163 * \frac{180}{\pi} = \boxed{9.354}^\circ$$

② (2)

$$\gamma = 2\tau + \alpha$$

$$45^\circ = 2 * 9.354 + \alpha$$

$$\alpha = \boxed{26.292}^\circ$$

③ (3)

$$P = Y_{sc} + R_c * (\cos \tau - 1)$$

$$= 6.21 + 350 * (\cos 9.354 - 1)$$

$$= \boxed{1.556} \text{ m}$$

④ (Lc, T, Es)

$$\alpha_{\text{rad}} = \alpha^\circ * \frac{\pi}{180} = 26.292 * \frac{\pi}{180} = 0.459 \text{ rad}$$

$$L_c = \alpha_{\text{rad}} * R_c = 0.459 * 350 = \boxed{160.65} \text{ m}$$

$$T = Y_{sc} + (P + R_c) * \tan\left(\frac{\gamma}{2}\right) - R_c * \sin \tau$$

$$= 113.97 + (1.556 + 350) * \tan\left(\frac{45}{2}\right) - 350 * \sin 9.354$$

$$= \boxed{202.7} \text{ m}$$

$$E_s = (P + R_c) * \sec\left(\frac{\gamma}{2}\right) - R_c$$

$$= (1.556 + 350) * \frac{1}{\cos\left(\frac{45}{2}\right)} - 350 = \boxed{30.52} \text{ m}$$

